
TOSVERT VF-AS1

Functions for lift application

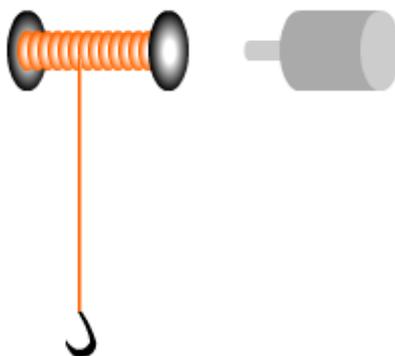
- Contents-

1. About using inverter to lifts application	2
2. Functions of VFAS1's for lift application.....	3
3. Standard connection.....	4
4. Parameter settings	5
5. Setting motor constants	7
6. Braking time learning.....	8
7. Light-load high-speed learning function	9

1. About using inverter to lifts application

The lift application such as crane and hoists is composed a gear motor with mechanical brake and lift equipment. It works by "winding up and down" and " inching" operation.

Fig.1 Outline chart of list application



The lift application with inverter drive, it has next merits compared than commercial power supply drive.

- To avoid shaking by starting shock.
- By braking at low speed, the maintenance of brake will be easy.
- Excessive power is not impressed to the wire rope. Therefore the maintenance of the wire rope will be easy.

2. Functions of VFAS1's for lift application

The TOSVERT VF-AS1 has next functions in standard model.

- Braking function
- Light-load high-speed operation function

Braking function:

This function can be used as brake sequences for lifts and similar equipment.

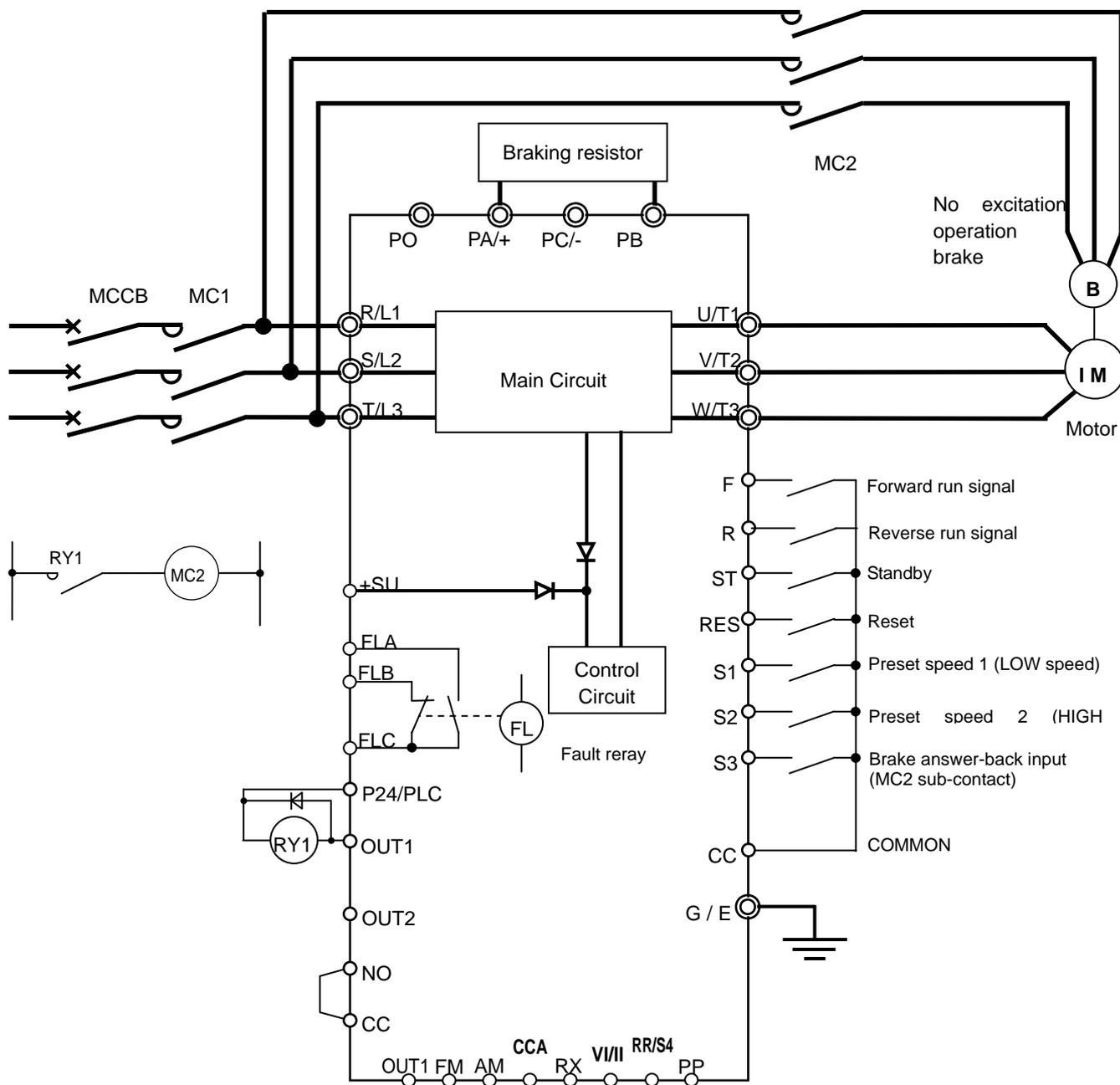
To ensure smooth operation, the motor produces enough torque before the brake is released.

Light-load high-speed operation function:

The light-load high-speed operation is used to improve the operating efficiency of the machine by increasing the rotational speed of the motor when it is operated under light load.

This function is useful for constant-torque load application which repeatedly drives light and heavy loads, such as lifts and transfer equipment.

3. Standard connection



[Operation] By terminal signal

[Speed reference] Preset speed 1 and 2, Operation panel → 3 preset speed

4. Parameter settings

At chapter 3, it is necessary to set next parameters.

Title	Functions	Setting range	Setting sample
<i>CMD</i>	Command mode selection	0:Terminal input enabled 1:Operation panel input enabled (including LED/LCD option input) 2:2-wire RS485 communication input 3:4-wireRS485 communication input 4:Communication option input	0
<i>FMD</i>	Frequency setting mode selection 1	1:V/I (voltage/current input) 2:RR/S4 (potentiometer/voltage input) 3:RX (voltage input) 4:Operation panel input enabled (including LED/LCD option input) 5:2-wire RS485 communication input 6:4-wire RS485 communication input	4
<i>LL</i>	Lower limit frequency	0.0 ~ Upper limit frequency	6.0
<i>ACC</i>	Acceleration time 1	0.1 ~ 6000 sec.	1.0
<i>DEC</i>	Deceleration time 1	0.1 ~ 6000 sec.	1.0
<i>Sr1</i>	Preset speed operation frequency 1	Lower limit frequency ~ Upper limit frequency	10.0
<i>Sr2</i>	Preset speed operation frequency 2	Lower limit frequency ~ Upper limit frequency	60.0
<i>Pb</i>	Dynamic braking selection	0:Deselect 1:Select (braking resistance overload detect) 2:Select (braking resistance overload not detect)	1
<i>Pbr</i>	Dynamic braking resistance	0.5 ~ 1000 ohm	Depends on capacity
<i>PbCP</i>	Allowable continuous braking resistance	0.01 ~ 600.0kW	Depends on capacity
<i>F117</i>	Input terminal function (S3)	0 ~ 135	130(Brake answer-back)
<i>F130</i>	Output terminal function (OUT1)	0 ~ 255	68(Brake release signal)
<i>F452</i>	Power running stall continuous trip detection time	0.0 ~ 1.0 sec.	0.5
<i>F453</i>	Regenerative braking stall prevention mode selection	0:Stall during regenerative braking 1:Not stall during regenerative braking	1
<i>F630</i>	Braking answer waiting time	0.0 ~ 10.0 sec.	0.5
<i>F305</i>	Overvoltage limit operation	0:Select 1:Deselect 2:Select (quick deceleration) 3:Select (dynamic quick deceleration)	1
<i>RU2</i>	Automatic torque boost	0:Deselect 1:Automatic torque boost + auto-tuning 1 2: Sensorless vector control 1+ auto-tuning 1	Refere chapter 5 note1)
<i>uL</i>	Base frequency 1	25.0 ~ 500Hz	Possible to use $RU2=2(Pt=3)$ in the following capacity range. - up to 200V 45kW - up to 400V 75kW
<i>uLv</i>	Base frequency voltage 1	200V class:50~330V 400V class:50~660V	
<i>Pt</i>	V/f control mode selection	3: Sensorless vector control 1 note1) 4: Sensorless vector control 2 8: PG feedback vector control 1	
<i>F400</i>	Auto-tuning 1	0:No auto-tuning 1:Initialize motor constant (0 after execution) 2:Continue operation continued after auto-tuning (0 after execution) 3:Auto-tuning by input terminal signal 4:Motor constant auto calculation (0 after execution)	
<i>F405</i>	Motor rated capacity	0.10 ~ 500.0 kW	
<i>F406</i>	Motor rated current	0.1 ~ 2000A	
<i>F407</i>	Motor rated capacity evolutions	100 ~ 60000min ⁻¹	

Title	Functions	Setting range	Setting sample
F328	Light-load high-speed operation selection	0:Deselect 1:High-speed operation speed set automatically (Power running at F command: Increase) 2:High-speed operation speed set automatically (Power running at R command: Increase) 3:High-speed operation speed set with F330 (Power running at F command: Increase) 4:High-speed operation speed set with F330 (Power running at R command: Increase)	Refere chapter 7
F329	Light-load high-speed learning function	0:No learning, 1:Forward run learning 2:Reverse run learning	
F330	Automatic light-load high-speed operation frequency	30.0 ~ Upper limit frequency Hz	
F331	Light-load high-speed operation switching lower limit frequency	30.0 ~ Upper limit frequency Hz	
F332	Light-load high-speed operation load waiting time	0.0 ~ 10.0 sec.	
F333	Light-load high-speed operation load detection time	0.0 ~ 10.0 sec.	
F334	Light-load high-speed operation heavy load detection time	0.0 ~ 10.0 sec.	
F335	Switching load torque during power running	-250 ~ 250%	
F336	Heavy-load torque during power running	-250 ~ 250%	
F337	Heavy-load torque during constant power running	-250 ~ 250%	
F338	Switching load torque during regenerative braking	-250 ~ 250%	
F341	Braking mode selection	0:Deselect, 1:Forward winding up 2:Reverse winding up 3:Horizontal operation (counter weight)	Refere chapter 6
F342	Load portion torque input selection	0:Disabled, 1:VI/II (voltage/current input) 2:RR/S4 (potentiometer/voltage input) 3:RX (voltage input) 4:343 enabled 5:2-wire RS485 communication input 6:4-wire RS485 communication input 7:Communications option input enabled 8:Optional AI1 (differential current input)	
F343	Hoisting torque bias input (valid only when F342=4)	-250 ~ 250%	
F344	Lowering torque bias multiplier	0 ~ 100%	
F345	Brake release time	0.00 ~ 2.50 sec.	
F346	Creeping frequency	F240 ~ 20.0Hz	
F347	Creeping time	0.00 ~ 2.50 sec.	
F348	Braking time learning function	0:Deselect, 1: Learning (0 after adjustment)	

5. Setting motor constants

It is necessary to set related parameters of vector control to use functions(Braking function and Light-load high-speed operation function) for lift application in VFAS1.

Note: In the following capacity range, don't use $PU2=2(Pt=3)$ setting.

- 200V-55kW or higher

- 400V-90kW or higher

This accuracy of vector control depends on parameters of motor constants ($F401$ to $F413$).

Moreover, the braking functions and Light-load high-speed operation depends on these parameters.

* The detail description of motor constants, please refer VFAS1's installation manual.

In this manual, the simple setting method is described.

Setting method of motor constants:

In case of using Pt (V/F control mode selection) = 4 (Sensor-less vector control 2)

1. Set next parameters that are described in motor's nameplate.

TOSHIBA 3 PHASE INDUSTRIAL MOTOR		OR	
RATED OUTPUT	15 kW 4 POLES	TYPE	TIKK
RATED VOLTAGE	200 200 220 V	FORM	FBKA21
RATED FREQUENCY	50 60 60 Hz	FRAME NO.	160L
RATED CURRENT	57.6 54.6 50.6 A	THERMAL CLASS	B
RATED SPEED	1440 1730 1740 min ⁻¹	RATING	S1
PROTECTION	IP44	BEARING	L.S. 6310ZZ
STANDARD	JIS C 4210 : 2001	NO.	O.S. 6208ZZ
SERIAL NO.			
TOSHIBA INDUSTRIAL PRODUCTS MANUFACTURING CORPORATION		MADE IN JAPAN	
M 04077			

TITLE	FUNCTIONS	Setting value
ωL	Base frequency 1	60
$\omega L \omega$	Base frequency volatge 1	200
$F405$	Motor rated capacity	15
$F406$	Motor rated current	54.6
$F407$	Motor rated capacity evolutions	1730

2. Set Pt to 4 and execute $F400$ to 4 (Automatic calculation of motor constants).
(Not to need motor wiring)
3. After motor wiring, set $F400$ to 2 (auto-tuning 1). After that, input operation signal.
(To input operation signal, the auto-tuning function is executes.)

6. Braking time learning

TOSVERT VF-AS1 has 'Braking time learning' function that automatically sets brake timing.

This function sets next parameters.

F345	Brake release time
F346	Creeping frequency
F347	Creeping time

* The details of braking functions, please refer VFAS1's installation manual .

In this manual, only described 'learning function' because of easy to set braking functions.

The operation of braking time learning:

1. Set F348 to 1. The learning function is enabled after operation signal input.

While learning, the LED display is indicated "L n" and "Operation frequency" each other.

2. It sets parameters F343 (Hoisting torque bias), and F345 (brake release time) by automatically measuring. In case of stop operation, F347 (creep time) is set.

NOTICE:

This learning function is necessary to execute the condition of light load. For example, it is only "Hook".

Sample of parameter setting at learning.

TITLE	FUNCTION	Setting range	Default setting	Setting sample
F341	Braking mode selection	0:Deselect, 1:Forward winding up 2:Reverse winding up 3:Horizontal operation (counter weight)	0	1
F342	Load portion torque input selection	0:Disabled, 1:VI/II (voltage/current input) 2:RR/S4 (potentiometer/voltage input) 3:RX (voltage input) 4:F343 enabled 5:2-wire RS485 communication input 6:4-wire RS485 communication input 7:Communications option input enabled 8:Optional AI1 (differential current input)	0	4
F343	Hoisting torque bias input (valid only when F342=4)	-250 ~ 250%	100%	100%
F344	Lowering torque bias multiplier	0 ~ 100%	100%	100%
F345	Brake release time	0.00 ~ 2.50 sec.	0.05 sec.	Auto
F346	Creeping frequency	F240 ~ 20.0Hz	3.0Hz	Auto
F347	Creeping time	0.00 ~ 2.50 sec.	0.10 sec.	Auto
F348	Braking time learning function	0:Deselect, 1: Learning (0 after adjustment)	0	1

7. Light-load high-speed learning function

TOSVERT VF-AS1 has "Light-load high-speed function" that is speed-up at light load for higher operation efficiency. Moreover, it has automatically setting mode to set light and heavy load switching that called "Light-load high-speed learning function".

* The details of "Light-load high-speed function", please refer VFAS1's installation manual.

In this manual, only described 'learning function' because of easy to set this functions.

Operation of Light-load high-speed learning function:

When the 60 Hz operation is normal speed, please set by next method.

1. Set $F330$ (Automatic light-load high-speed operation frequency).

ex. $F330 = 90$ Hz

2. Set $F329$ (Light-load high-speed learning function) to 1 (Learning only forward run).

3. Confirm to switch high-speed (90Hz) at forward run (60Hz) with maximum light-load.

While learning, the 7 segment LEDs are indicated "t" and "operation frequency".

4. Set $F329$ (Light-load high-speed learning function) to 2 (Learning only reverse run).

5. Confirm to switch high-speed (90Hz) at reverse run (60Hz) with maximum light-load.

While learning, the 7 segment LEDs are indicated "t" and "operation frequency".

6. After this operation, next parameters are set automatically.

TITLE	FUNCTIONS	Default setting	Set value at learning function
$F335$	Switching load torque during power running	50	Motoring torque + 5% (Load torque monitor 1 for light-load/high-speed)
$F336$	Heavy-load torque during power running	100	Motoring torque + 5% (Load torque monitor 2 for light-load/high-speed)
$F337$	Heavy-load torque during constant power running	50	Maximum acceleration torque value between motoring normal speed and high-speed (Speed attainment)
$F338$	Switching load torque during regenerative braking	50	Regenerating torque + 5% (Load torque monitor 1 for light-load/high-speed)

7. Confirm that is not to switch high-speed with heavy-load.

8. In lift-up from ground, confirm to switch normal speed after high-speed operation.

From ground: Usually, it will be high-speed because low wire tension.

NOTICE:

In case of next learning result, VF-AS1 doesn't switch high-speed.

The learning function is finished after stop operation.

- Switching load torque during power running: Over 70%
- Switching load torque during regenerative braking: Over 70%

In case of detection torque over 150% at high-speed, it stops high-speed operation and learning data isn't memorized.

Case of the detection torque is over 100% at constant speed after high-speed acceleration, it stops high-speed operation and learning data don't memory.

Setting sample: (Set at learning)

TITLE	FUNCTIONS	Setting range	Default setting	Setting sample
<i>F328</i>	Light-load high-speed operation selection	0:Deselect 1:High-speed operation speed set automatically (Power running at F command: Increase) 2:High-speed operation speed set automatically (Power running at R command: Increase) 3:High-speed operation speed set with <i>F330</i> (Power running at F command: Increase) 4:High-speed operation speed set with <i>F330</i> (Power running at R command: Increase)	0	1
<i>F329</i>	Light-load high-speed learning function	0:No learning, 1:Forward run learning 2:Reverse run learning	0	1 or 2
<i>F330</i>	Automatic light-load high-speed operation frequency	30.0 ~ Upper limit frequency Hz	60.0Hz	60.0Hz
<i>F331</i>	Light-load high-speed operation switching lower limit frequency	30.0 ~ Upper limit frequency Hz	40.0Hz	40.0Hz
<i>F332</i>	Light-load high-speed operation load waiting time	0.0 ~ 10.0 sec.	0.5 sec.	0.5 sec.
<i>F333</i>	Light-load high-speed operation load detection time	0.0 ~ 10.0 sec.	1.0 sec.	1.0 sec.
<i>F334</i>	Light-load high-speed operation heavy load detection time	0.0 ~ 10.0 sec.	0.5 sec.	0.5 sec.
<i>F335</i>	Switching load torque during power running	-250 ~ 250%	50%	AUTO
<i>F336</i>	Heavy-load torque during power running	-250 ~ 250%	100%	AUTO
<i>F337</i>	Heavy-load torque during constant power running	-250 ~ 250%	50%	AUTO
<i>F338</i>	Switching load torque during regenerative braking	-250 ~ 250%	50%	AUTO